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HoCL High level specification of dataflow graphs

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GdR ISIS 2020-11-18

Introduction

Question I

Q: What are the three most things in programming?

A:

- I. abstraction
- 2. abstraction
- 3. abstraction

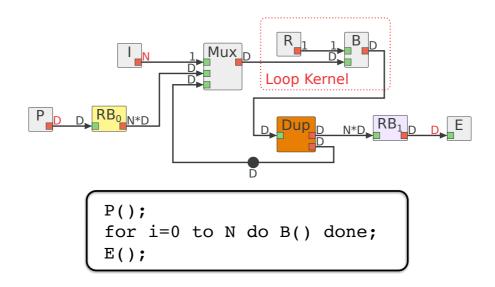
Question 2

Q: Do dataflow models promote abstraction?

A: Well, it depends...

EXAMPLE I

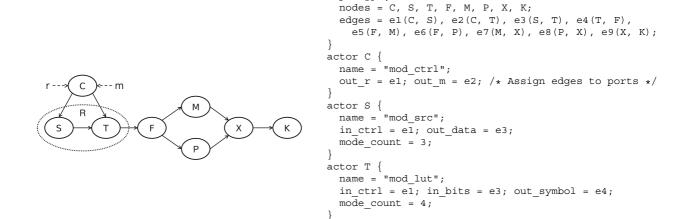
Dataflow formulation of an iterative algorithm in Preesm https://preesm.github.io



Source: Extensions and Analysis of Dataflow Models of Computation for Embedded Runtimes.. PhD thesis. F. Arrestier, 2020.

EXAMPLE 2

Dataflow formulation of an RMOD application in DIF (Dataflow Interchange format)



/* ... */

/* Other actor definitions */

CFDF RMOD {
 topology {

Source: The DSPCAD Framework for Modeling and Synthesis of Signal Processing Systems. Shuoxin Lin, Yanzhou Liu, Kyunghun Lee, Lin Li, William Plishker, and Shuvra S. Bhattacharyya, 2017.

Motivations

- Simplify the specification of large and complex dataflow graphs
- Independently of the underlying dataflow model of computation
 - pure coordination language (..CL = Coordination Language)
- Support for hierarchical and parameterized graphs
- Independently of the target implementation platform (software, hardware, mixed, ...)
- Support for mixed-style descriptions (structural or functional)

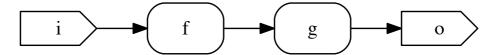
This presentation

- Informal presentation of the language by means of small examples
- Technical details such as typing, semantics, etc. deliberately omitted
 - https://github.com/jserot/hocl

Core features



Example I



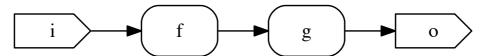
```
node f
  in (i: int) out(o: int);

node g
  in (i: int) out(o: int);

graph top
  in (i: int)
  out (o: int)
struct
  wire w: int
  box n1: f(i)(w)
  box n2: g(w)(o)
end;
```

- This defines a graph top, with input i and output o.
- This graph is built from two boxes,
 n1 and n2, linked by a wire w
- Boxes and wires are typed
- Each box is an instance of a node (f and g resp.)
- Nodes f and g are here defined as opaque actors (black boxes)
- The graph top is here defined structurally

Example I



```
node f
  in (i: int)
  out(o: int);

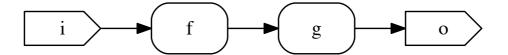
node g
  in (i: int)
  out(o: int);

graph top
  in (i: int)
  out (o: int)
fun
  val o = g (f i)
end;
```

- This is an alternative description of graph top using a functional style
- Nodes are interpreted as functions and the graph is described using function application
 - applying function f to value x (here denoted as f x) builds a node by instantiating actor f and connecting the wire representing the value x to its input
- An actor with m inputs e₁:t₁, ..., e_m:t_m and n inputs s₁:t'₁, ..., s_n:t'_m is interpreted as a (curried) function of type

$$e_1:t_1 \rightarrow ... \rightarrow e_m:t_m \rightarrow t'_1 * ... * t'_m$$

Example I



```
node f
   in (i: int)
   out(o: int);

node g
   in (i: int)
   out(o: int);

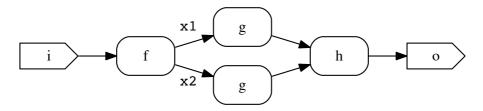
graph top
   in (i: int)
   out (o: int)
fun
   val o = i |> f |> g
end;
```

• Another functional formulation using the reverse application operator |>:

$$x \mid > f = f x$$

Example 2

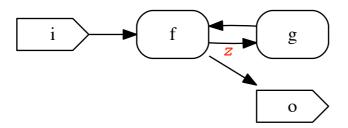
A slightly more complex graph



```
node f in (i: int) out (o1: int, o2:int);
node g in (i: int) out (o: int);
node h in (i1: int, i2:int) out (o:int);
```

```
graph top
  in (i: int)
  out (o: int)
fun
  val (x1,x2) = f i
  val o = h (g x1) (g x2)
end;
```

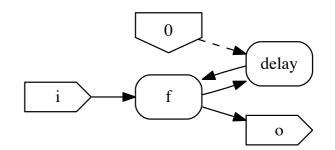
Cycles and recursive wiring



```
node f in (i1: t1, i2: t2) out (o1: t4, o2: t3);
node g in (i: t3) out (o: t2);
```

```
graph top
  in (i: t1) out (o: t4)
fun
  val rec (o,z) = f i (g z)
end;
```

Delayed cycles



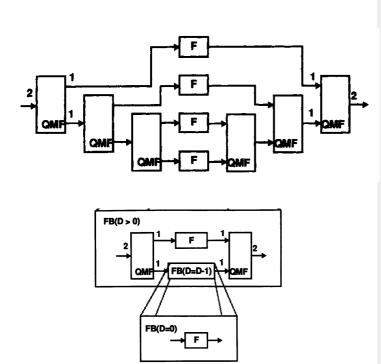
```
graph top
  in (i: int) out (o: int)
fun
val rec (o,z) = f (i, delay '0' z)
end;
```

```
graph top
  in (i: int) out (o: int)
struct
  wire w1, w2: int
  box n1: f(i,w1)(o,w2)
  box n2: delay('0',w2)(w1)
end;
```

- Delays are required to avoid deadlock when **simulating** the graph (they provide the initial token(s) on the feedback edge(s)
- The special actor *delay* is predefined (and interpreted specifically by the various backends)
 - the actor parameter ('0', here) specifies the initial value)
- Using type or application specific delay actors is also possible

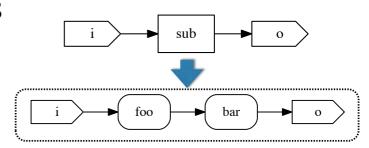
Recursive graphs

Example (from [Lee and Parks, 1995])



```
node f
  in (i: t)
 out (o: t);
node qmf
  in (i: t)
 out (o1: t, o2: t);
graph top
   in (i: t)
  out (o: t)
 val rec fb d x =
   if d = 0 then f x
   else
    let x1, x2 = qmf x in
    qmf (f x1)
        (fb (d-1) x2)
  val o = fb 3 i
end;
```

Hierarchical graphs



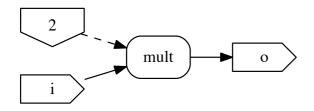
```
node foo in (i: t) out (o: t);
node bar in (e: t) out (s: t);

node sub in (i: t) out (o: t)
fun
   val o = i |> foo |> bar
end;

graph top in (i: t) out (o: t)
fun
   val o = i |> sub
end;
```

- Nodes can be described as (sub)graphs (either structurally or functionally), giving rise to hierarchical graphs
- Node with no description are interpreted as opaque actors (« blackboxes »)
- Toplevel graphs are identified with the graph keyword

Parameters



```
node mult
  in (k: int param, i: int)
  out (o: int);

graph top
  in (i: int) out (o: int)
fun
  val o = i |> mult '2'
end;
```

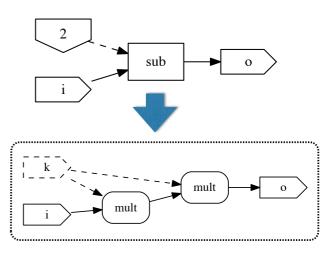
- Parameters are used to configure (specialize) nodes
- Parameters are distinguished from data by their type :
 - t param is the type of a parameter having itself type t
- In functional descriptions, this allows specifying their value using partial application of the corresponding function

Parameter passing

• Parameters can be passed from one hierarchy level to a nested one

```
node sub
  in (k: int param, i: int)
out (o: int)
fun
  val o =
    i |> mult k |> mult k
end;

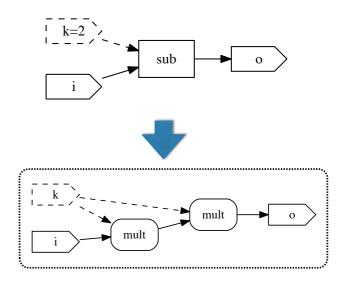
graph top
  in (i: int) out (o: int)
fun
  val o = i |> sub '2'
end;
```



Parameter passing

```
node sub
    in (k: int param, i: int)
    out (o: int)
fun
    val o =
        i |> mult k |> mult k
    end;

graph top
    in (k: int param=2, i: int)
    out (o: int)
fun
    val o = i |> sub k
    end;
```

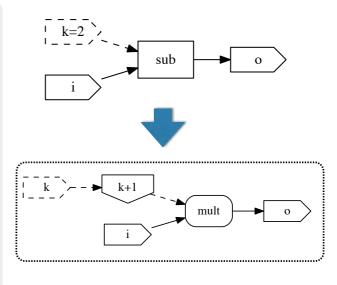


• The value of the toplevel parameters can be defined in the corresponding graph interface

Parameter dependencies

```
node sub
   in (k: int param, i: int)
   out (o: int)
fun
   val o =
        i |> mult 'k+1'
end;

graph top
   in (k: int param=2, i: int)
   out (o: int)
fun
   val o = i |> sub k
end;
```

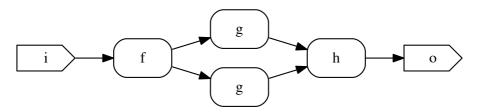


- The value of some parameters can depend on that of other parameters, defined at the same or at higher level(s) in the graph hierarchy
- Dependencies between parameter values create a *tree* in graph, which is "orthogonal" to the data flow

Higher order features Ho..



Wiring functions

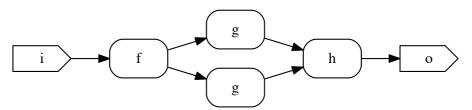


Another formulation:

```
graph top
  in (i: int)
  out (o: int)
fun
  val body x =
  let (x1,x2) = f x in
  h (g x1) (g x2)
  val o = body i
end;
```

- body is a wiring function: it encapsulates the wiring pattern of the encoded graph
- The definition of body makes use of a local definition (let .. in)
- The top graph is built by simply applying this function
- Wiring functions can be defined within a (sub)graph (local scope) or globally

Higher order wiring functions

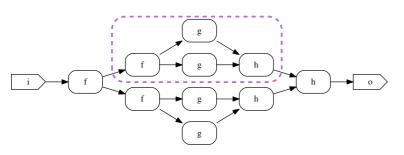


Pushing the abstraction a bit further:

```
graph top
  in (i: int)
  out (o: int)
fun
  val diamond left middle right x =
  let (x1,x2) = left x in
  right (middle x1) (middle x2)
  val o = diamond f g h i
end;
```

- The diamond function abstracts further the definition of body, by taking as parameters the actors to be instantiated to build the defined graph
- The graph top is built by supplying the actual actors (f, g and h) as arguments to diamond.
- diamond is an higherorder wiring function (HOWF)

Higher order wiring functions



```
graph top
  in (i: int) out (o: int)
fun
  val diamond l m r x = ...
  val sub = diamond f g h
  val o = diamond f sub h i
end;
```

```
graph top
  in (i: int) out (o: int)
struct
  wire w1, w2, w3, w4,
       w5, w6, w7, w8,
       w9,w10,w11,w12:int
  box f1: f(i)(w1, w2)
  box f2: f(w1)(w3,w4)
  box f3: f(w2)(w5, w6)
  box g1: g(w3)(w7)
  box g2: g(w4)(w8)
  box g3: g(w5)(w9)
  box g4: g(w6)(w10)
  box h1: h(w7, w8)(w11)
  box h2: h(w9, w10)(w12)
  box h3: h(w11, w12)(0)
end;
```

- The diamond function is here instantiated at two levels :
 - within the sub function, to describe the « inner » diamond structure
 - within the definition of the output o, to build the toplevel graph structure

« Classic » higher order wiring functions

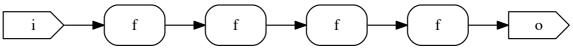
- Many recurrent graph patterns can be encapsulated using higher-order wiring functions
- Example:

```
i f1 f2 f3 o
```

```
graph top
   in (i: int)
   out (o: int)
fun
   val o = i |> pipe [f1;f2;f3]
end;
```

« Classic » higher order wiring functions

- Many recurrent graph patterns can be encapsulated using higher-order wiring functions
- Example:



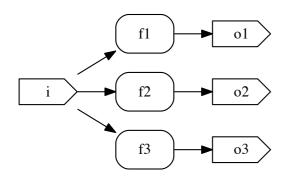
```
graph top
   in (i: int)
   out (o: int)
fun
   val o = i |> iter 4 f
end;
```

where:

```
val rec iter n f x =
  if n = 0 then x
  else iter (n-1) f (f x)
```

« Classic » higher order wiring functions

- Many recurrent graph patterns can be encapsulated using higher-order wiring functions
- Example :



```
graph top
  in (i:int)
  out (o1:int, o2:int, o3:int)
fun
  val (o1,o2,o3) =
    i |> mapf [f1;f2;f3]
end;
```

```
where: val rec mapf fs x = match fs with
        [] -> []
        | f::fs' -> f x :: mapf fs' x;
```

Higher order wiring functions

- Higher order wiring functions
 - promote abstraction
 - allow common graph patterns to be encapsulated for reuse
- In HoCL, they are defined within the language itself
 - the set of available reusable patterns can therefore be freely extended to suit the application domain
 - this is in contrast with existing dataflow-based design tools in which similar abstraction mechanisms rely on a predefined and fixes set of patterns

In practice

Implementation

- Prototype compiler written in OCaml
- Based upon a fully formalized static semantics (natural style)
- Source code available on github (jserot/hocl)
- Two versions
 - a command line compiler
 - a toplevel interpreter
- The CL compiler currently has four backends
 - a .dot backend (for visualizing the DFGs)
 - a DIF backend (for interfacing to DF-based analysis tools)
 - a Preesm backend (for generating code on heterogeneous many-core embedded platforms)
 - a SystemC backend (for simulation under the DDF and SDF MoCs)

Example: using the SystemC backend

Used to simulate the described DFGs

Example

- Initialisation and per-activation code provided as external C functions
- Automatic generation of FIFOs, delay, broadcast and IO nodes (reading/writing files)

```
node foo
  in (i: int) out (o: int)
actor
  systemc(
    loop_fn="foo",
    incl_file="foo.h",
    src_file="foo.cpp")
end;

graph top
  in (i: int) out (o: int)
fun
  val o = i |> foo
end;
  main.hcl
```

foo

:int

:int

```
void foo(IN int *i, OUT int *o)
  { *o = *i * 2; }

1 2 3 4 ...

bash> hoclc -systemc main.hcl

# Wrote file systemc/main_top.cpp

# Wrote file systemc/top_gph.h

# Wrote file systemc/foo_act.h

# Wrote file systemc/foo_act.cpp

bash> cd ./systemc; make

2 4 6 8 ...

top_o.dat
```

void foo(IN int *i, OUT int *o);

foo.h

Conclusion

- Another attempt to bring the benefits of functional programming outside its « classical » circle
 - programmers in the DSP field are *not* familiar with concepts such as polymorphic typing and higher order functions
- Drawing of previous experience in a similar context with the CAPH project (http://dream.ispr-ip.fr/CAPH)
 - provide interfaces to existing, already used, tools
 - demonstrate practical benefits wrt. this tools
 - introduce disruptive concepts only if it serves a well identified goal

Conclusion

- Work in progress
 - injection of MoC-specific features into specifications
 - design of large scale DSP applications with HoCL for assessing gains if programmer's productivity

Thanks for your (remote) attention